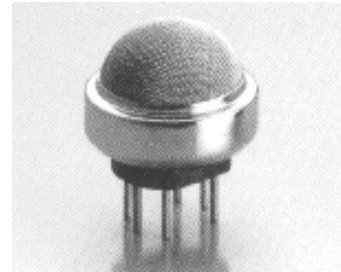


Technical Information for Ammonia Sensors

Figaro TGS 8-series sensors are a type of sintered bulk metal oxide semiconductor which offer low cost, long life, and good sensitivity to target gases while utilizing a simple electrical circuit. The TGS826 displays high sensitivity to ammonia.



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See also Technical Brochure 'Technical Information on Usage of TGS Sensors for Toxic and Explosive Gas Leak Detectors'.

IMPORTANT NOTE: OPERATING CONDITIONS IN WHICH FIGARO SENSORS ARE USED WILL VARY WITH EACH CUSTOMER'S SPECIFIC APPLICATIONS. FIGARO STRONGLY RECOMMENDS CONSULTING OUR TECHNICAL STAFF BEFORE DEPLOYING FIGARO SENSORS IN YOUR APPLICATION AND, IN PARTICULAR, WHEN CUSTOMER'S TARGET GASES ARE NOT LISTED HEREIN. FIGARO CANNOT ASSUME ANY RESPONSIBILITY FOR ANY USE OF ITS SENSORS IN A PRODUCT OR APPLICATION FOR WHICH SENSOR HAS NOT BEEN SPECIFICALLY TESTED BY FIGARO.

1. Basic Information and Specifications

1-1 Features

- * High sensitivity to amine compounds
- * Quick response to low concentrations of ammonia
- * Uses simple electrical circuit
- * Ceramic base resistant to severe environment

1-2 Applications

- * Ammonia leak detection in refrigerators
- * Ventilation control for the agricultural and poultry industries

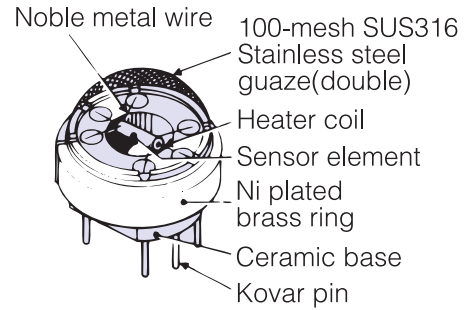
1-3 Structure

Figure 1 shows the structure of TGS826. This sensor is a sintered bulk semiconductor composed mainly of metal oxide. The semiconductor material and electrodes are formed on an alumina ceramic tube. A heater coil is located inside the ceramic tube. Lead wires from the sensor electrodes are a gold alloy. Heater and lead wires are connected to the sensor pins which have been arranged to fit a 7-pin miniature tube socket.

The sensor base is made of a ceramic base which can withstand environments as high as 200°C. The upper and lower openings in the sensor case are covered with a flameproof double layer of 100 mesh stainless steel gauze (SUS316). Independent tests confirm that this mesh will prevent a spark produced inside the flameproof cover from igniting an explosive 2:1 mixture of hydrogen/oxygen.

1-4 Basic measuring circuit

Figure 2 shows the basic measuring circuit for use with TGS826. Circuit voltage (Vc) is applied across the sensor element which has a resistance between the sensor's two electrodes and the load resistor (RL) connected in series. The sensor signal (VRL) is measured indirectly as a change in voltage across the RL. Since the sensor has a polarity, DC voltage should always be applied for circuit voltage (a white dot indicates pin #2). The Rs is obtained from the formula shown at the right.



Sensor element

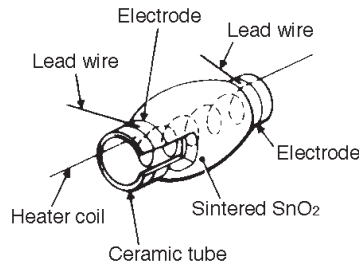


Fig. 1 - Sensor structure

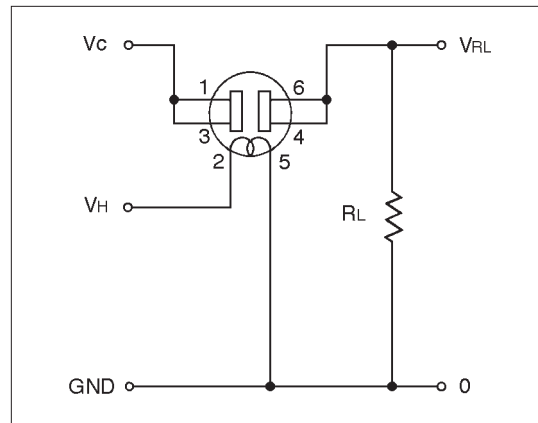


Fig. 2 - Basic measuring circuit (pin #2 is indicated by a white dot on the sensor's base)

$$R_s = \frac{V_c - V_{RL}}{V_{RL}} \times R_L$$

Formula to determine Rs

1-5 Circuit & operating conditions

The ratings shown below should be maintained at all times to insure stable sensor performance:

Item	Specification
Circuit voltage (V _c)	Max. 24V (DC only)
Heater voltage (V _H)	5.0V ± 0.2V AC/DC
Heater resistance (room temp)	30 ± 3Ω
Load resistance (R _L)	variable (P _s ≤ 15mW)
Operating temperature	30°C ~ 50°C
Storage temperature	-40°C ~ +80°C
Optimal detection concentration	30 ~ 300ppm

1-6 Specifications NOTE 1

Item	Specification
Sensor resistance (50ppm ammonia)	20kΩ ~ 100kΩ
Sensor resistance ratio (R _s /R _o)	0.55 ± 0.15
R _s /R _o = R _s (150ppm ammonia)/R _s (50ppm ammonia)	
Heater current (R _H)	approx. 167mA
Heater power consumption (P _H)	approx. 833mW

Mechanical Strength:

The sensor shall have no abnormal findings in its structure and shall satisfy the above electrical specifications after the following performance tests:

- Withdrawal Force - withstand force of 5kg in each direction (pin from base)
- Vibration - frequency-1000c/min., total amplitude-4mm, duration-one hour, direction-vertical
- Shock - acceleration-100G, repeated 5 times

1-7 Dimensions

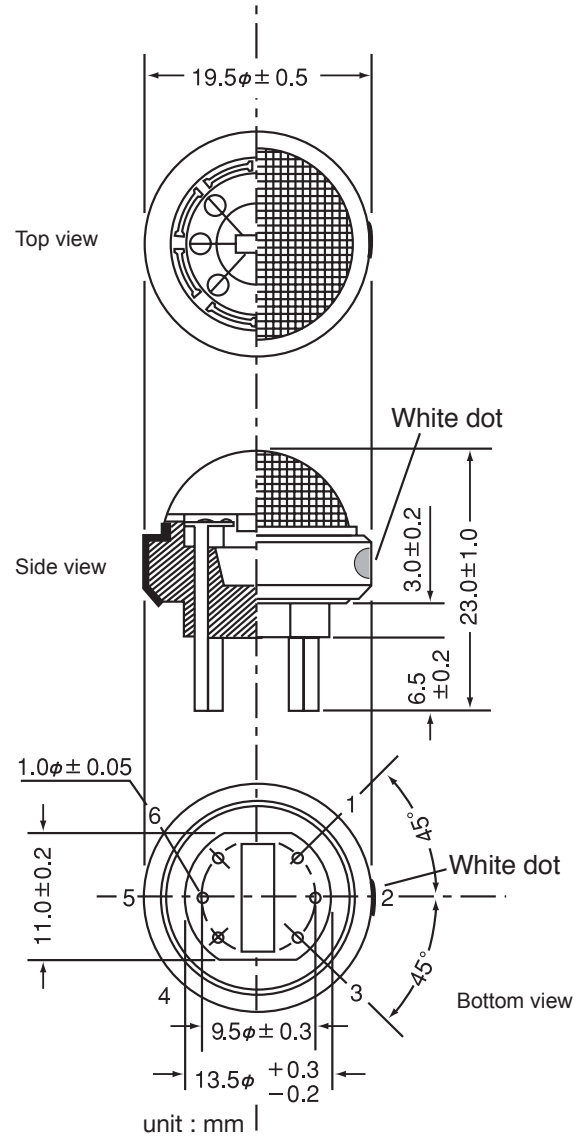


Fig. 3 - Sensor dimensions

NOTE 1: Sensitivity characteristics are obtained under the following standard test conditions:

(Standard test conditions)

Temperature and humidity: 20 ± 2°C, 65 ± 5% RH

Circuit conditions: V_c = 5.0 ± 0.01V DC

V_H = 5.0 ± 0.05V DC

R_L = 33kΩ ± 1%

Preheating period: 7 days or more under standard circuit conditions

2. Typical Sensitivity Characteristics

2-1 Sensitivity to various gases

Figure 4 shows the relative sensitivity of TGS826 to various gases. The Y-axis shows the ratio of the sensor resistance in various gases (R_s) to the sensor resistance in 50ppm of ammonia (R_o).

Using the basic measuring circuit illustrated in Figure 2, together with a matched RL value equivalent to the R_s value in 50ppm of ammonia, will provide the sensor output voltage (V_{RL}) change as shown in Figure 5.

NOTE:

All sensor characteristics in this technical brochure represent typical sensor characteristics. Since the R_s or output voltage curve varies from sensor to sensor, calibration is required for each sensor (for additional information on calibration, please refer to the Technical Advisory 'Technical Information on Usage of TGS Sensors for Toxic and Explosive Gas Leak Detectors').

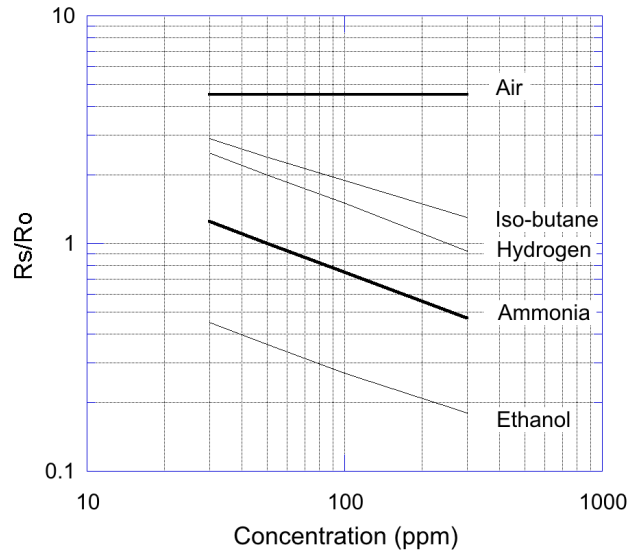


Fig. 4 - Sensitivity to various gases (R_s/R_o)

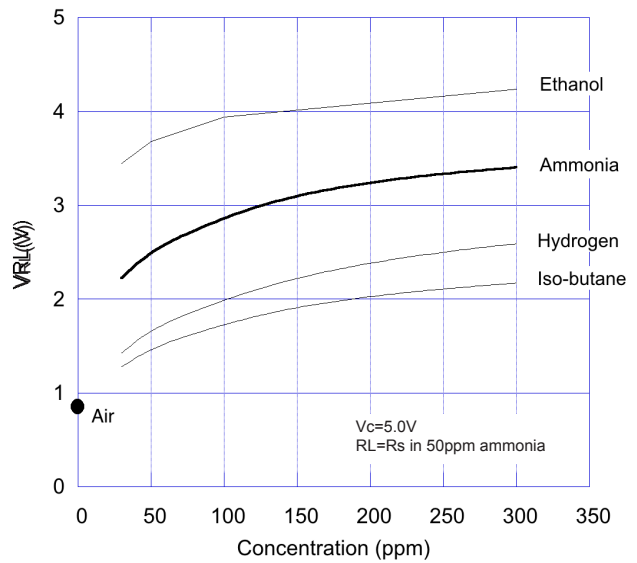


Fig. 5 - Sensitivity to various gases (V_{RL})

2-2 Temperature and humidity dependency

Figure 6 shows the temperature and humidity dependency of TGS826. The Y-axis shows the ratio of sensor resistance in 150ppm of ammonia under various atmospheric conditions (R_s) to the sensor resistance in 150ppm of ammonia at 20°C/65%RH (R_o).

RH (°C)	0% RH	20%RH	40%RH	65%RH	100%RH
-30					1.41
-20					1.29
-10					1.19
0					1.09
10					1.00
20	1.22	1.13	1.06	1.05	0.92
30	1.15	1.06	1.00	0.97	
40	1.07	1.00	0.95	0.91	
50	1.02	0.96	0.92	0.86	

Table 1 - Temperature and humidity dependency
(typical values of R_s/R_o for Fig. 6)

Table 1 shows a chart of values of the sensor's resistance ratio (R_s/R_o) under the same conditions as those used to generate Figure 6.

2-3 Heater voltage dependency

Figure 7 shows the change in the sensor resistance ratio according to variations in the heater voltage (V_H).

Note that 5.0V as a heater voltage must be maintained because variance in applied heater voltage will cause the sensor's characteristics to be changed from the typical characteristics shown in this brochure.

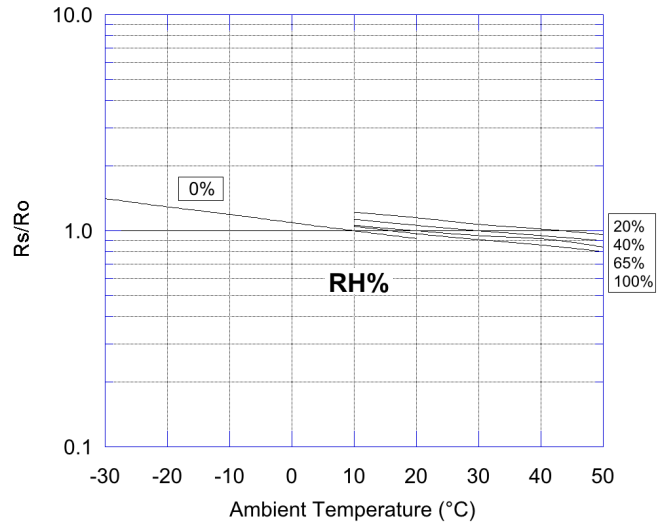


Fig. 6 - Temperature and humidity dependency (R_s/R_o)

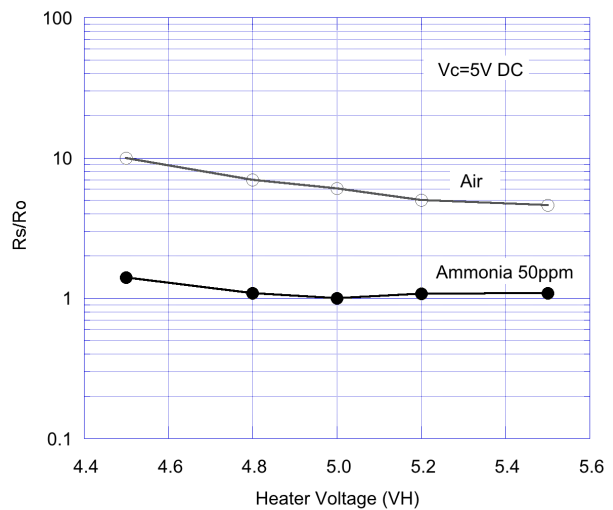


Fig. 7 - Heater voltage dependency
($R_s = R_s$ in 50ppm of ammonia,
 $R_o = R_s$ at 50ppm ammonia and $V_H=5.0V$ DC)

2-4 Gas response

Figure 8 shows the change pattern of sensor resistance (R_s) when the sensor is inserted into and later removed from 50 and 150ppm of ammonia.

As this chart displays, the sensor's response speed to the presence of gas is extremely quick, and when removed from gas, the sensor will recover back to its original value in a short period of time.

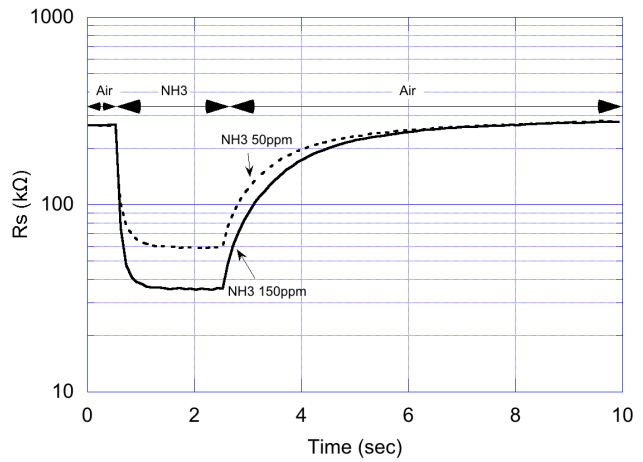


Fig. 8 - Response speed

2-6 Initial action

Figure 9 shows the initial action of the sensor resistance (R_s) for a sensor which is stored unenergized in normal air for 30 days and later energized in clean air.

The R_s drops sharply for the first seconds after energizing, regardless of the presence of gases, and then reaches a stable level according to the ambient atmosphere. Such behavior during the warm-up process is called "Initial Action".

Since this 'initial action' may cause a detector to alarm unnecessarily during the initial moments after powering on, it is recommended that an initial delay circuit be incorporated into the detector's design (refer to *Technical Advisory 'Technical Information on Usage of TGS Sensors for Toxic and Explosive Gas Leak Detectors'*). This is especially recommended for intermittent-operating devices such as portable gas detectors.

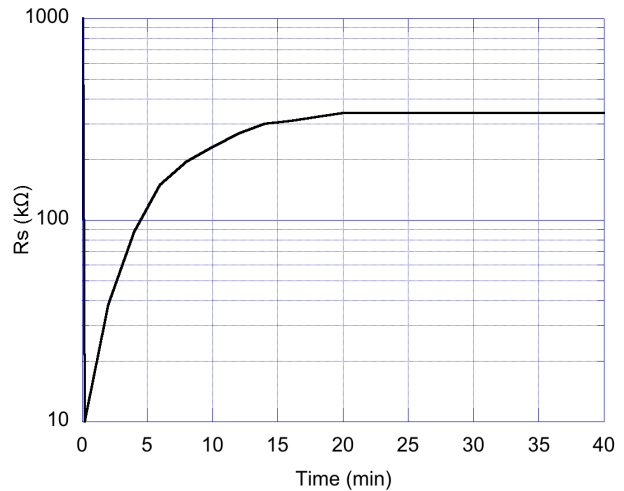


Fig. 9 - Initial action

2-7 Long-term characteristics

Figure 10 shows long-term stability of TGS826. The sensor is first energized for 7 days in normal air. Measurement for confirming sensor characteristics is conducted under ambient air conditions rather than in a temperature/humidity controlled environment. The cyclic change in sensitivity corresponds to the seasonal changes of temperature/humidity in Japan (peak T/H conditions occur in July, as corresponds with the sensitivity peaks in this chart). The Y-axis represents the ratio of sensor resistance in 50 and 150ppm of ammonia on the date tested (Rs) to sensor resistance in air at the beginning of the test period (Ro).

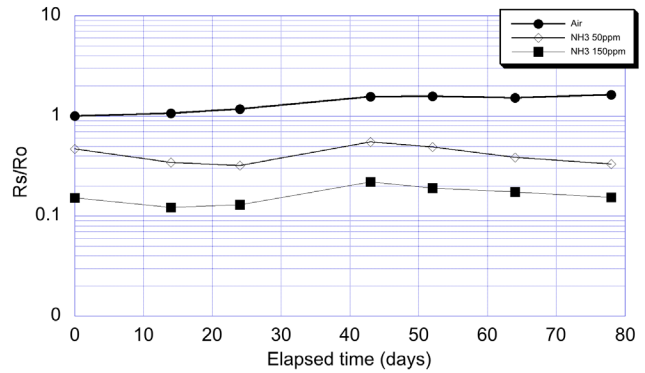


Fig. 10 - Long term stability--continuous energizing (Ro = Rs in air on day 1)

Figure 11 shows the influence of storage in an unenergized condition on the sensor's resistance. Sensors were stored unenergized in air after 7 days of energizing. Then, sensors were energized for one hour before measurement was taken.

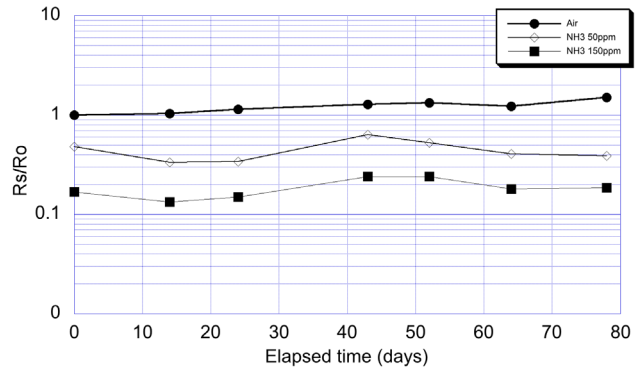


Fig. 11 - Long term stability - influence of unenergized state (Ro = Rs in air on day 1)

3. Reliability

3-1 Gas exposure test

Figure 12 shows the effects of long-term exposure to high concentrations of ammonia. Sensors were energized for 7 days in normal air before measurement was taken. Then, sensors were energized in 1000ppm of ammonia for 35 days. Measurements in air and ammonia were taken after energizing in normal air for one hour.

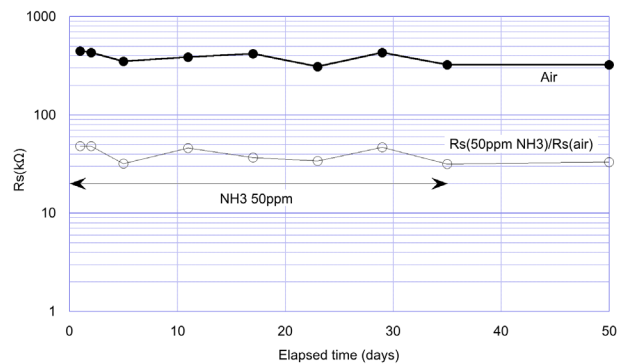


Fig. 12 - Gas exposure test

4 Cautions

4-1 Situations which must be avoided

1) Exposure to silicone vapors

If silicone vapors adsorb onto the sensor's surface, the sensing material will be coated, irreversibly inhibiting sensitivity. Avoid exposure where silicone adhesives, hair grooming materials, or silicone rubber/putty may be present.

2) Highly corrosive environment

High density exposure to corrosive materials such as H₂S, SO_x, Cl₂, HCl, etc. for extended periods may cause corrosion or breakage of the lead wires or heater material.

3) Contamination by alkaline metals

Sensor drift may occur when the sensor is contaminated by alkaline metals, especially salt water spray. This may also happen if the sensor is exposed to inorganic elements.

4) Contact with water

Sensor drift may occur due to soaking or splashing the sensor with water.

5) Freezing

If water freezes on the sensing surface, the sensing material would crack, altering characteristics.

6) Application of excessive voltage

If higher than specified voltage is applied to the sensor or the heater, lead wires and/or the heater may be damaged or sensor characteristics may drift, even if no physical damage or breakage occurs.

7) Operation in zero/low oxygen environment

TGS sensors require the presence of around 21% (ambient) oxygen in their operating environment in order to function properly and to exhibit characteristics described in Figaro's product literature. TGS sensors cannot properly operate in a zero or low oxygen content atmosphere.

8) Application of voltage on lead wires

On six-pin type sensors, if a voltage is applied on the lead wires between pins 1 and 3 and/or pins 4 and 6, this would cause breakage of the lead wires (see Fig. 13).

4-2 Situations to be avoided whenever possible

1) Water condensation

Light condensation under conditions of indoor usage should not pose a problem for sensor performance. However, if water condenses on the sensor's surface and remains for an extended period, sensor characteristics may drift.

2) Usage in high density of gas

Sensor performance may be affected if exposed to a high density of gas for a long period of time, regardless of the powering condition.

3) Storage for extended periods

When stored without powering for a long period, the sensor may show a reversible drift in resistance according to the environment in which it was stored. The sensor should be stored in a sealed bag containing clean air; do not use silica gel. *Note that as unpowered storage becomes longer, a longer preheating period is required to stabilize the sensor before usage.*

4) Long term exposure in adverse environment

Regardless of powering condition, if the sensor is exposed in extreme conditions such as very high humidity, extreme temperatures, or high contamination levels for a long period of time, sensor performance will be adversely affected.

5) Vibration

Excessive vibration may cause the sensor or lead wires to resonate and break. Usage of compressed air drivers/ultrasonic welders on assembly lines may generate such vibration, so please check this matter.

6) Shock

Breakage of lead wires may occur if the sensor is subjected to a strong shock.

7) Soldering

Ideally, sensors should be soldered manually. For soldering conditions of 8-series gas sensors, refer to

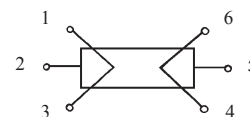


Fig. 13 - TGS826 pin configuration

Technical Advisory for Soldering 8-type Gas Sensors.

8) Polarity

If the polarity of Vc is reversed during powering, sensor characteristics may temporarily become unstable.

Special Note: A more narrowly defined range of Rs or Rs/Ro will be indicated on each production lot (*see Appendix*). Preselected ranges of Rs or Rs/Ro are **not** available.

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Appendix

TGS 826 Pre-Sorted Groupings

The TGS 826 sensor has a wide specification range in terms of its rated value in 50ppm of NH₃ and sensor resistance ratio (Rs in 150ppm of NH₃ / Rs in 50ppm of NH₃). To facilitate usage of this sensor, TGS 826 is shipped in pre-sorted groupings of 20 pieces per bag, with each bag marked with one of the following group numbers which indicate a more narrow range within the specification.

Please be advised that the sensor is produced to meet the overall specification range--production of specific groupings within the spec cannot be done.

Group #	Rs in 50ppm of NH ₃ (kΩ)			Rs (in 150ppm of NH ₃)		
				Rs (in 50ppm of NH ₃)		
1-A	20 ~ 30			0.4 ~ 0.5		
1-B	20 ~ 30				0.5 ~ 0.6	
1-C	20 ~ 30					0.6 ~ 0.7
2-A		30 ~ 40		0.4 ~ 0.5		
2-B		30 ~ 40			0.5 ~ 0.6	
2-C		30 ~ 40				0.6 ~ 0.7
3-A			40 ~ 53	0.4 ~ 0.5		
3-B			40 ~ 53		0.5 ~ 0.6	
3-C			40 ~ 53			0.6 ~ 0.7
4-A	53 ~ 70			0.4 ~ 0.5		
4-B	53 ~ 70				0.5 ~ 0.6	
4-C	53 ~ 70					0.6 ~ 0.7
5-A		70 ~ 85		0.4 ~ 0.5		
5-B		70 ~ 85			0.5 ~ 0.6	
5-C		70 ~ 85				0.6 ~ 0.7
6-A			85 ~ 100	0.4 ~ 0.5		
6-B			85 ~ 100		0.5 ~ 0.6	
6-C			85 ~ 100			0.6 ~ 0.7